

Brianna Gopaul *Engineering Physicist*

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📍 Vancouver

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👤 [BriannaGopaul](#)

Skills

Electrical Engineering

Altium, Reading
Datasheets

Mechanical

SolidWorks,
Laser/Waterjet Cutting,
Machining

Software

Python, Java, OpenCV,
Tensorflow, Keras

Misc

PCR, Gel Electrophoresis,
UHV Vacuum Equipment

Professional Experience

Research Assistant, *Yachie Lab, UBC SBME*

05/2023 – 08/2023

- Designed and conducted wet lab experiments for DNA GPS [🔗](#), a novel large-scale optics-free spatial transcriptomic technique, using PCR, Gel Electrophoresis and other common wet lab techniques
- Reviewed biotech literature and wrote internal research documents to evaluate modern transcriptomic sequencing techniques

Research Intern, *Cambridge Existential Risk Initiative*

05/2022 – 08/2022

- Led a 10-week research project on identifying technological bottlenecks in biosurveillance systems to prevent future pandemics under Akhil Bhansal
- Published report [🔗](#) that investigates the core technological bottlenecks in metagenomic sequencing technology for use in clinical and environmental settings

R&D Engineering Intern, *General Fusion*

05/2021 – 08/2021

- Conducted material science experiments to find suitable plasma-facing components for General Fusion's commercial fusion reactor involving UHV Vacuum systems, liquid lithium evaporation setups, and more
- Designed and assembled a functioning liquid lithium syringe in Solidworks to dispense controlled amounts of lithium

Highschool AI Research Intern, *SanctuaryAI*

07/2020 – 08/2020

- Implemented variational autoencoders and used transformers under Dr.Geordie Rose to create better attention mechanisms

Highschool Research Intern, *Xanadu*

07/2019 – 08/2019

- Wrote documentation for Strawberry Fields a photonic quantum computing package, for visualizing quantum circuits and quantum states: CV Quantum Gate Visualization [🔗](#)

Projects

License Plate Scanning AI, *Python, OpenCV, ROS, Gazebo, Tensorflow*

- Programmed and trained a robot using ROS and Tensorflow that used a Soft Actor Critic model to drive autonomously inside a Gazebo simulation. The robot was able to detect and read license plates using OpenCV and a CNN built in Keras.
- Got first place in ENPH353 Competition

Autonomous Overcooked Robot, *Altium, Solidworks, C++*

- Designed various PCBs in Altium: H Bridge, IR Sensing with electronic filtering, Tape Following
- Debugged protoboards and PCBs using oscilloscope
- Robot got fourth place in ENPH253 competition

Inertial Confinement Fusor, *Vacuum, High Voltage, Soldering,*

- Built an inertial confinement fusor (small fusion reactor) in my basement.
- Fusor Progress Video [🔗](#) (project halted due to undergraduate degree and internship)

Education

University of British Columbia, B.ASc Engineering Physics [↗](#) 2021 – 2026

Focus on foundational and upper-level mathematics and physics with a blend of Electrical Engineering, Mechanical Engineering and Software Engineering. Often described as a mechatronics degree + physics degree hybrid.

Awards

Emergent Ventures Fellow, Mercatus Center 2021

Grant program that supports entrepreneurs and brilliant minds with highly scalable, "zero to one" ideas for meaningfully improving society.